## ICFP Masters program

École Normale Supérieure
M1 (Fall/Winter 2015/2016)

## Final Exam: Mathematical Aspects of Symmetries in Physics

This exam is closed book, closed notes. It consists of three pages. You have 3 hours. Carefully justify each step in your reasoning. Good luck!

## 1 Finite groups and representations

## 1. Conjugacy classes

Let $G$ denote a finite group. Recall that $x^{G}$ denotes the equivalence class of $x \in G$ with regard to conjugation, and $Z(G)$ denotes the center of $G$.
(a) Prove that $\left|x^{G}\right|=1 \Leftrightarrow x \in Z(G)$.
(b) Prove the following equation, known as the class equation: Let $x_{1}, \ldots, x_{l}$ be representatives of the conjugacy classes of $G$. Then

$$
|G|=|Z(G)|+\sum_{x_{i} \notin Z(G)}\left|x_{i}^{G}\right| .
$$

(c) Let $p$ be a prime number (in French: nombre premier), and let $n$ be a positive integer. Suppose that $G$ is a group of order $p^{n}$.
i. Use the class equation to show that $Z(G) \neq\{e\}$.
ii. Suppose that $n \geq 3$ and that $|Z(G)|=p$. Prove that $G$ has a conjugacy class of size $p$.

## 2. Equivariance, one dimensional representations

(a) Let $\left(\rho_{V}, V\right)$ and $\left(\rho_{W}, W\right)$ be two representations of a finite group $G$, and $\varphi: V \rightarrow W$ an invertible equivariant map. Let $\left\{v_{i}\right\}$ and $\left\{w_{j}\right\}$ be sets of basis vectors of $V, W$ respectively. Let $\mathcal{M}^{V}, \mathcal{M}^{W}, \mathcal{M}^{\varphi}$ be the matrix representations of the functions $\rho_{V}, \rho_{W}, \varphi$ with regard to the respective bases. Express $\mathcal{M}^{W}$ in terms of $\mathcal{M}^{V}$ and $\mathcal{M}^{\varphi}$.
(b) Let $\rho_{1}, \rho_{2}: G \rightarrow \mathbb{C}-\{0\}$ be one-dimensional representations of a finite group $G$. Show that $\rho_{1}$ is equivalent to $\rho_{2}$ if and only if $\rho_{1}=\rho_{2}$.
(c) Let $G$ be a finite group.
i. Let $g \in G$. Prove that the set $\left\{g^{1}, g^{2}, \ldots, g^{n}\right\}$ for an appropriate positive integer $n$ carries a group structure. Characterize the minimal such $n$. It is called the order of the element $g$.
ii. Let $\rho$ be a one-dimensional representation of the group $G$, and suppose that $g \in G$ has order $n$. Show that $\rho(g)$ is an $n^{t h}$-root of unity.
iii. Construct $n$ inequivalent one-dimensional representations of the group $\mathbb{Z} / n \mathbb{Z}$.
iv. Explain why no further one-dimensional representations of $\mathbb{Z} / n \mathbb{Z}$ exist.

## 3. Characters

(a) A certain group $G$ of order 12 is known to have a total of four conjugacy classes, with representatives $g_{1}, \ldots, g_{4}$. Three of its four irreducible characters take the following values:

| $g_{i}$ | $g_{1}=e$ | $g_{2}$ | $g_{3}$ | $g_{4}$ |
| :---: | :---: | :---: | :---: | :---: |
| $\left\|C_{G}\left(g_{i}\right)\right\|$ | 12 | 4 | 3 | 3 |
| $\chi_{1}$ | 1 | 1 | 1 | 1 |
| $\chi_{2}$ | 1 | 1 | $\omega$ | $\omega^{2}$ |
| $\chi_{3}$ | 1 | 1 | $\omega^{2}$ | $\omega$ |

We have here denoted $\omega=e^{2 \pi i / 3}$. Note that beneath each representative $g_{i}$ of a conjugacy class, we have given the order of the corresponding centralizer. Using the appropriate orthogonality relation of characters, find the complete character table of $G$. Justify each entry for $\chi_{4}$.
(b) Let $\psi$ be the class function on $G$ taking the following values:

$$
\begin{array}{c|cccc}
g_{i} & g_{1}=e & g_{2} & g_{3} & g_{4} \\
\hline \psi & 0 & 0 & 1+2 \omega-\omega^{2} & 1-\omega+2 \omega^{2}
\end{array}
$$

Express $\psi$ as a linear combination of $\chi_{1}, \ldots, \chi_{4}$. Is $\psi$ a character of $G$ ?

## 2 Differential manifolds, Lie groups, and Lie algebras

## 1. Differentiable structure on the real line

Let $\mathbb{R}$ be the real line with the differentiable structure given by the maximal atlas containing the chart $(\mathbb{R}, \varphi=i d: \mathbb{R} \rightarrow \mathbb{R})$, and let $\mathbb{R}^{\prime}$ be the real line with the differentiable structure given by the maximal atlas containing the chart $\left(\mathbb{R}^{\prime}, \psi: \mathbb{R}^{\prime} \rightarrow \mathbb{R}\right)$, where $\psi(x)=x^{1 / 3}$.
(a) Show that these two differentiable structures are distinct.
(b) Show that there exists a diffeomorphism between $\mathbb{R}$ and $\mathbb{R}^{\prime}$. The two differentiable structures are thus equivalent.

## 2. Vector spaces as differentiable manifolds

Let $V$ be a $d$-dimensional real vector space. Let $\left\{e_{i}\right\}$ be a set of basis vectors for $V$, with dual basis $\left\{u_{i}\right\}$. Let $p \in V$, and $X \in T_{p} V$.
(a) Explain why the dual basis defines global coordinate functions on $V$.
(b) Write down an isomorphism between $T_{p} V$ and $V$.
(c) Assume $X$ has the expansion

$$
X=\left.\sum_{i=1}^{d} a_{i} \frac{\partial}{\partial u_{i}}\right|_{p}
$$

in terms of the basis of $T_{p} V$ induced by the coordinate functions $u_{i}$. Let $\left\{\tilde{e}_{i}\right\}$ be a second set of basis vectors for $V$, with $e_{i}=\sum_{j=1}^{d} A_{i j} \tilde{e}_{j}, i=1, \ldots, d$. By acting on a $C^{\infty}$ function $f \in \mathcal{F}_{p}$, find the expression for $X$ in the basis induced by the dual basis $\left\{\tilde{u}_{i}\right\}$ to $\left\{\tilde{e}_{i}\right\}$.
(d) By considering the two expressions for $X$ thus obtained, prove that the isomorphism you introduced above between $T_{p} V$ and $V$ is basis independent.

## 3. Lie algebra structure on $\mathbb{R}^{2}$

(a) Let $(x, y),(v, w) \in \mathbb{R}^{2}$. Define the bracket

$$
[(x, y),(v, w)]=(0, x w-y v) .
$$

Show that $\left(\mathbb{R}^{2},[\cdot, \cdot]\right)$ defines a Lie algebra.
(b) Let $\mathfrak{g}$ be a 2-dimensional Lie algebra, spanned by basis vectors $\{e, f\}$ satisfying $[e, f]=f$. Prove that it is isomorphic as a Lie algebra to the one above.
(c) Prove that up to isomorphism, only two different Lie algebra structures can be imposed on the vector space $\mathbb{R}^{2}$.

## 4. Homomorphisms between Lie groups induce homomorphisms between Lie algebras

Let $\varphi: G \rightarrow H$ be a Lie group homomorphism. Then

$$
d \varphi: T_{e_{G}} G \rightarrow T_{e_{H}} H
$$

as $\varphi\left(e_{G}\right)=e_{H}$. By means of the natural identifications $\mathfrak{g} \cong T_{e_{G}} G, \mathfrak{h} \cong T_{e_{H}} H, d \varphi$ thus induces a linear transformation of $\mathfrak{g}$ into $\mathfrak{h}$, which we also call $d \varphi$ :

$$
d \varphi: \mathfrak{g} \rightarrow \mathfrak{h} .
$$

(a) Explain why for a given $X \in \mathfrak{g}, d \varphi(X)$ thus defined is the unique left-invariant vector field on $H$ such that

$$
d \varphi(X)\left(e_{H}\right)=d \varphi\left(X\left(e_{G}\right)\right)
$$

(b) Let $G$ and $H$ be Lie groups with Lie algebras $\mathfrak{g}$ and $\mathfrak{h}$ respectively, and let $\varphi: G \rightarrow H$ be a Lie group homomorphism. Prove the following:
i. $X$ and $d \varphi(X)$ are $\varphi$-related for any $X \in \mathfrak{g}$.
ii. The mapping $d \varphi: \mathfrak{g} \rightarrow \mathfrak{h}$ is a Lie algebra homomorphism.

