Problem Set for Exercise Session No.5

Course: Mathematical Aspects of Symmetries in Physics, ICFP Master Program (for M1) 18th December, 2014, at Room 235A

Lecture by Amir-Kian Kashani-Poor (email: kashani@lpt.ens.fr) Exercise Session by Tatsuo Azeyanagi (email: tatsuo.azeyanagi@phys.ens.fr)

1 Some Basics on Manifolds

Answer the following questions:

(1) Here we confirm in two ways that a two-sphere with unit radius, $S^2 = \{(x, y, z) \in \mathbb{R}^3 | x^2 + y^2 + z^2 = 1\}$, is a two-dimensional differentiable manifold of class C^{∞} .

1. We take an atlas $\{(O_x^{\pm}, \varphi_x^{\pm}), (O_y^{\pm}, \varphi_y^{\pm}), (O_z^{\pm}, \varphi_z^{\pm})\}$ where the open sets are defined by

$$\begin{split} O_x^+ &= \{(x,y,z) \in S^2 | x > 0\}\,, \qquad O_x^- &= \{(x,y,z) \in S^2 | x < 0\}\,, \\ O_y^+ &= \{(x,y,z) \in S^2 | y > 0\}\,, \qquad O_y^- &= \{(x,y,z) \in S^2 | y < 0\}\,, \\ O_z^+ &= \{(x,y,z) \in S^2 | z > 0\}\,, \qquad O_z^- &= \{(x,y,z) \in S^2 | z < 0\}\,. \end{split}$$

and $\varphi_x^{\pm}, \varphi_y^{\pm}, \varphi_z^{\pm}$ are maps from the corresponding open sets to a two-dimensional open disk $D^2 = \{(a, b) \in \mathbb{R}^2 | a^2 + b^2 < 1\}$:

$$\begin{split} \varphi_x^+(x, y, z) &= \varphi_x^-(x, y, z) = (y, z) \,, \\ \varphi_y^+(x, y, z) &= \varphi_y^-(x, y, z) = (x, z) \,, \\ \varphi_z^+(x, y, z) &= \varphi_z^-(x, y, z) = (x, y) \,. \end{split}$$

By using this atlas, compute the transition functions to confirm that S^2 is a twodimensional differentiable manifold of class C^{∞} .

2. Let us consider another atlas $\{(U^{\pm}, f^{\pm})\}$ for S^2 where the open sets are defined by

$$U^{\pm} = S^2 \setminus \{(0, 0, \pm 1)\},\$$

and f^{\pm} are stereographic projections of S^2 from $(0, 0, \pm 1)$ to (x, y)-plane. By using this atlas, confirm that S^2 is a two-dimensional differentiable manifold of class C^{∞} .

(2) Let us consider a two-dimensional real projective space $\mathbb{R}P^2$ defined as a quotient of $\mathbb{R}^3 \setminus \{(0,0,0)\}$ under the equivalence relation

$$(x,y,z) \quad \sim \quad (x',y',z') \quad \Leftrightarrow \quad (x',y',z') = \lambda(x,y,z) \,, \qquad \lambda \in \mathbb{R} \setminus \{0\} \,,$$

for $(x, y, z), (x', y', z') \in \mathbb{R}^3 \setminus \{(0, 0, 0)\}$. We denote the equivalence class for (x, y, z) by [x : y : z].

1. We take an atlas $\{(U_x, \varphi_x), (U_y, \varphi_y), (U_z, \varphi_z)\}$ where the open sets are given by

$$U_x = \{ [x:y:z] \in \mathbb{R}P^2 | x \neq 0 \}, \ U_y = \{ [x:y:z] \in \mathbb{R}P^2 | y \neq 0 \}, \ U_z = \{ [x:y:z] \in \mathbb{R}P^2 | z \neq 0 \},$$

and the maps from these open sets to \mathbb{R}^2 as

$$\varphi_x([x:y:z]) = \left(\frac{y}{x}, \frac{z}{x}\right), \qquad \varphi_y([x:y:z]) = \left(\frac{x}{y}, \frac{z}{y}\right), \qquad \varphi_z([x:y:z]) = \left(\frac{x}{z}, \frac{y}{z}\right)$$

Compute the transition functions to confirm that $\mathbb{R}P^2$ is a two-dimensional differentiable manifold of class C^{∞} .

2. Let us consider a quotient of S^2 by the equivalence relation

$$(x,y,z) \quad \sim \quad (x',y',z') \quad \Leftrightarrow \quad (x',y',z') = \pm (x,y,z) \,,$$

for $(x, y, z), (x', y', z') \in S^2$ (that is, identify the antipodal points). We denote this quotient of S^2 as S^2/\sim . Show that $\mathbb{R}P^2$ is homeomorphic to S^2/\sim .

2 Tangent Vector

Let us consider a point $p = (\sin \phi_0, 0, \cos \phi_0)$ (for $\phi_0 \in (0, \pi]$) on $S^2 = \{(x, y, z) \in \mathbb{R}^3 | x^2 + y^2 + z^2 = 1\}$ and a curve $c : (-\epsilon, \epsilon) \to S^2$ (for $\epsilon > 0$) defined by

$$c(t) = (\sin \phi_0 \cos t, \sin \phi_0 \sin t, \cos \phi_0).$$

We note that this curve satisfies c(t = 0) = p. Write down the tangent vector to this curve at p by using the coordinate introduced in Problem 1 (1)-2 through the stereo-graphic projection from the north pole $(0, 0, 1) \in S^2$.

Note on Revision

Janurary 23 2015

Some problems in Problem 2 (in the old version) are moved to Problem Set No.7 and 8.